

Fig. 1

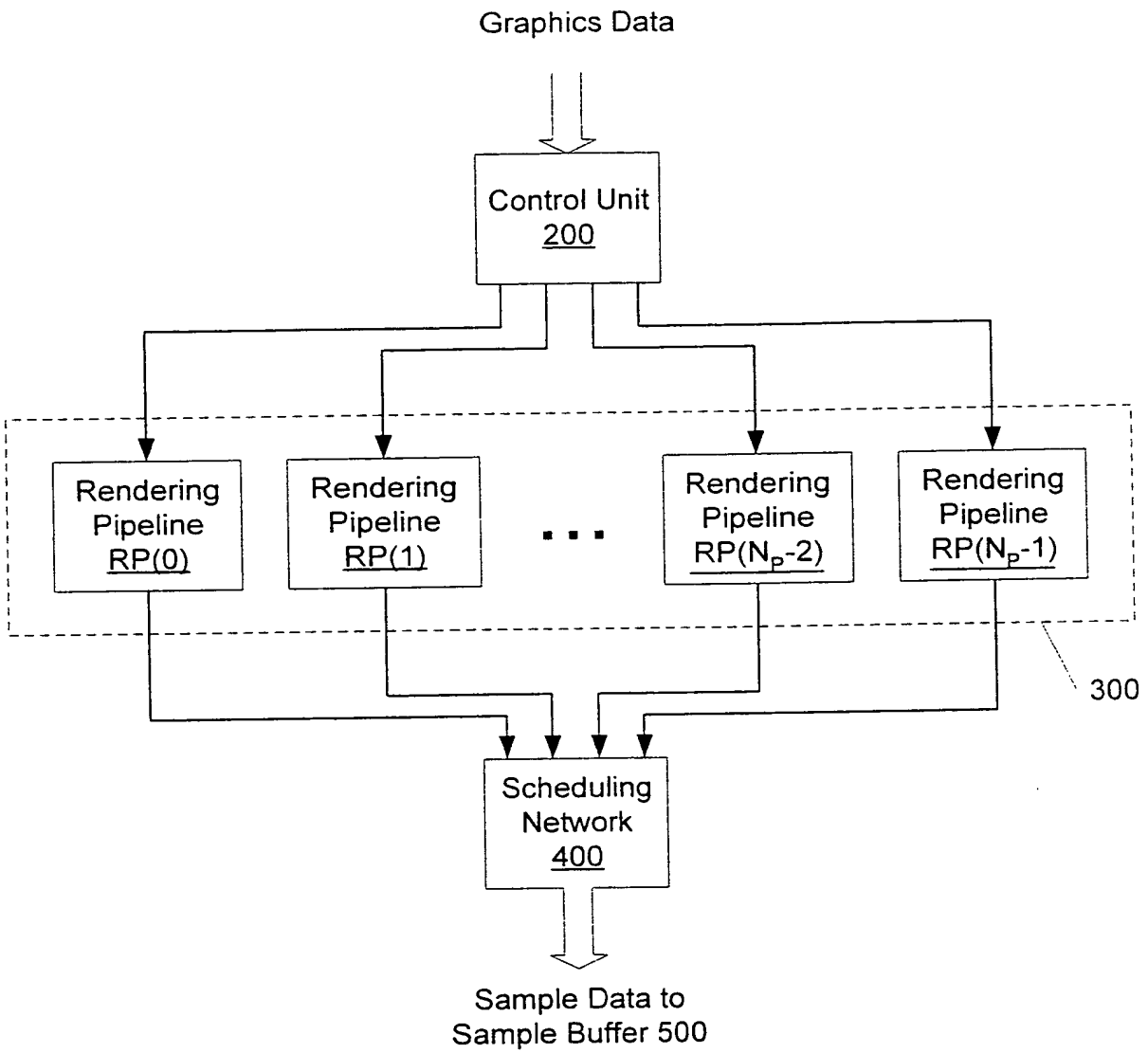


Fig. 2

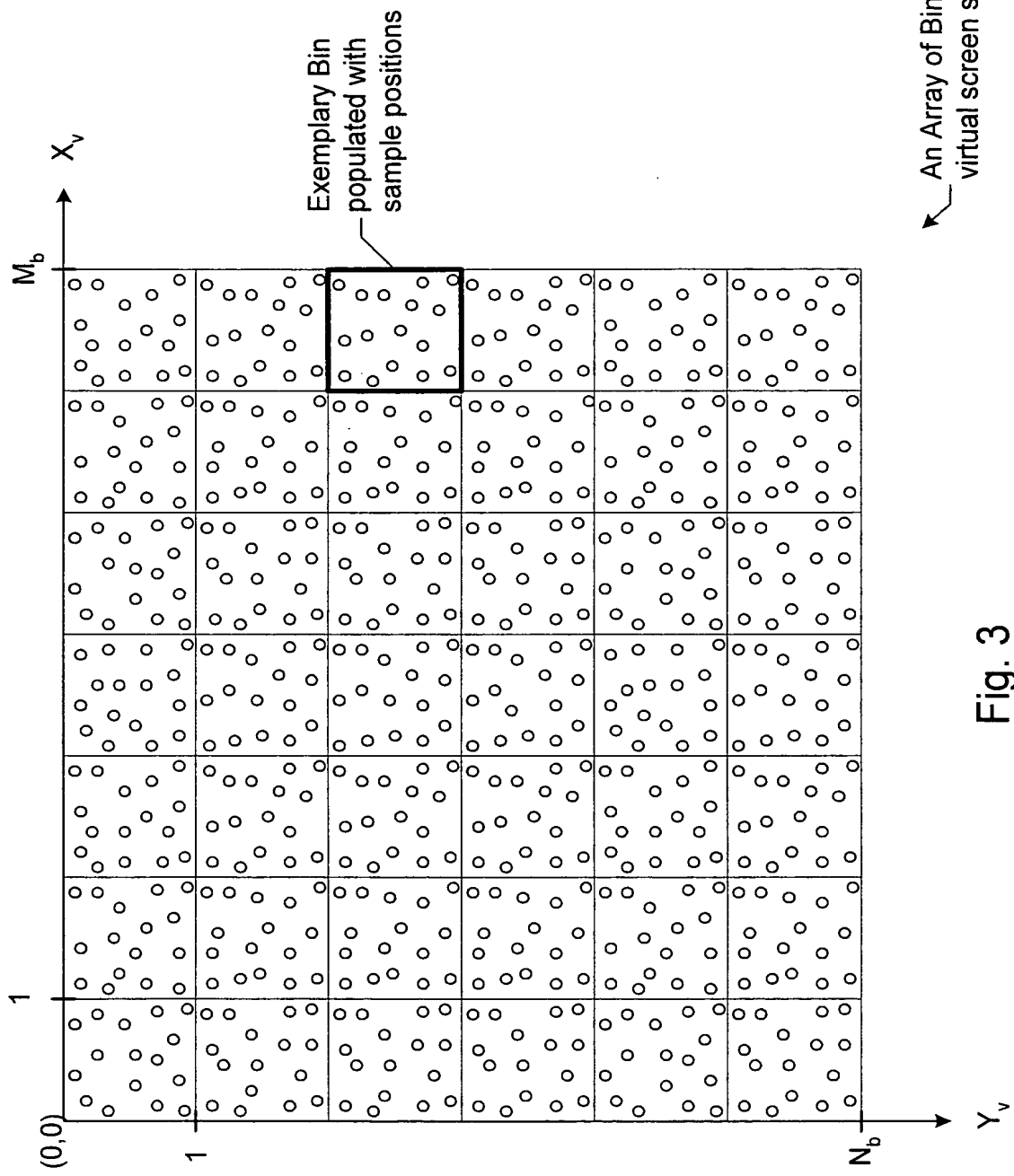


Fig. 3

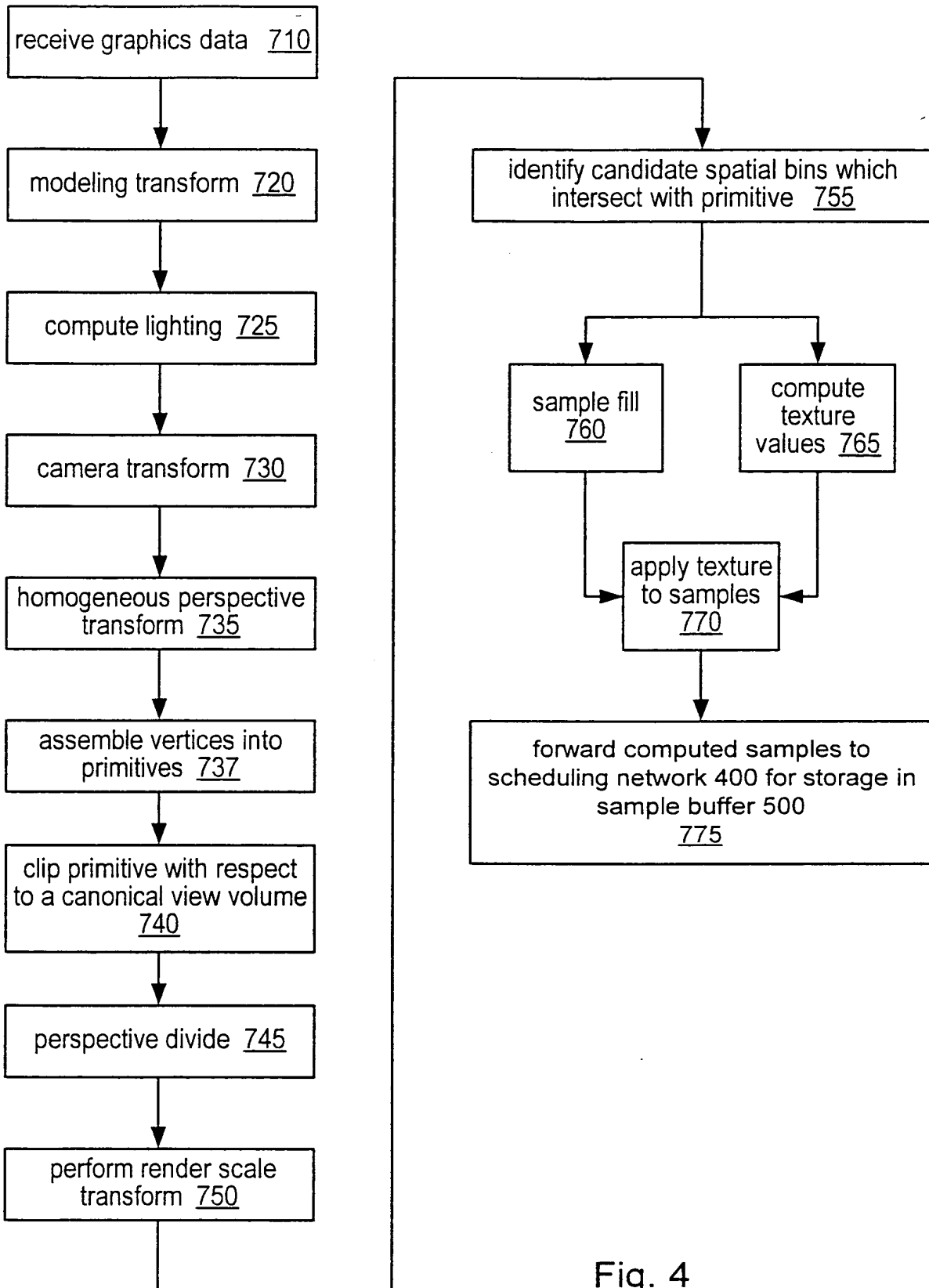


Fig. 4

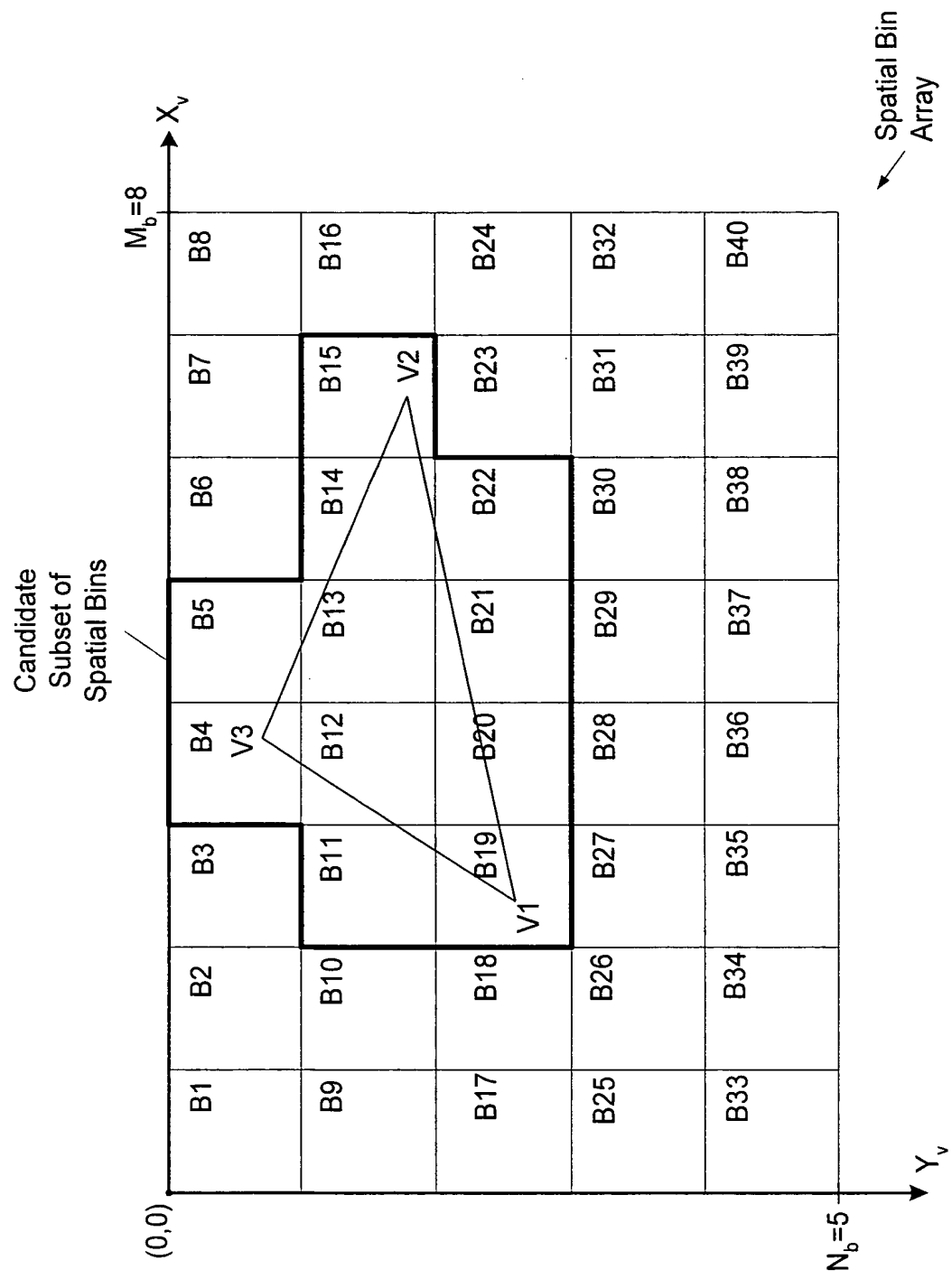


Fig. 5

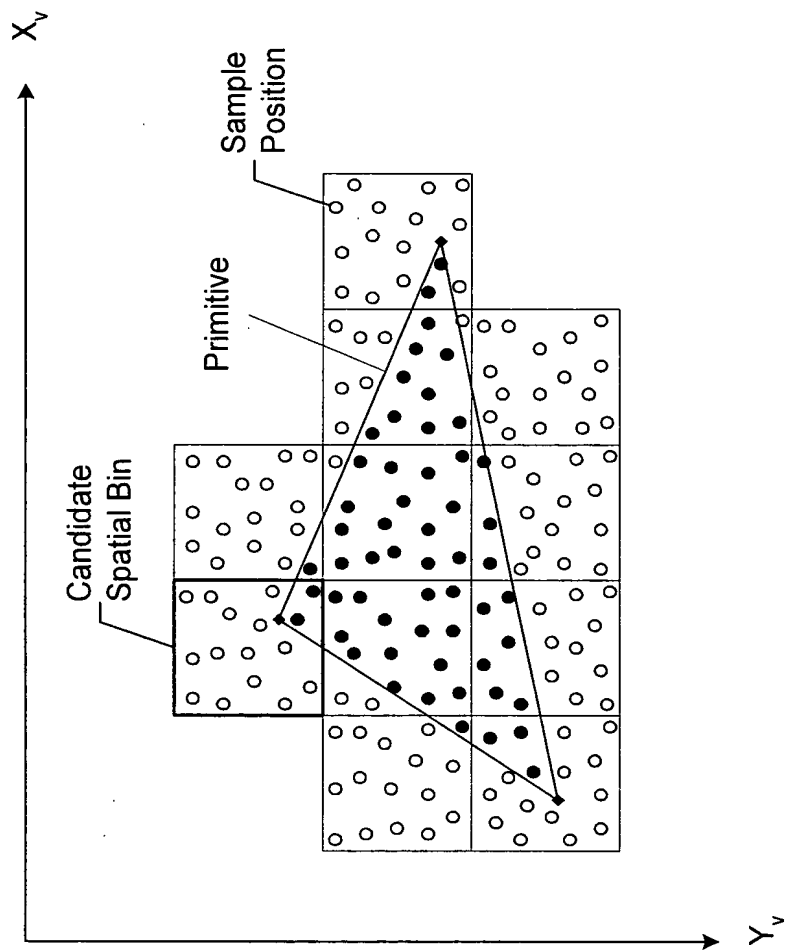


Fig. 6

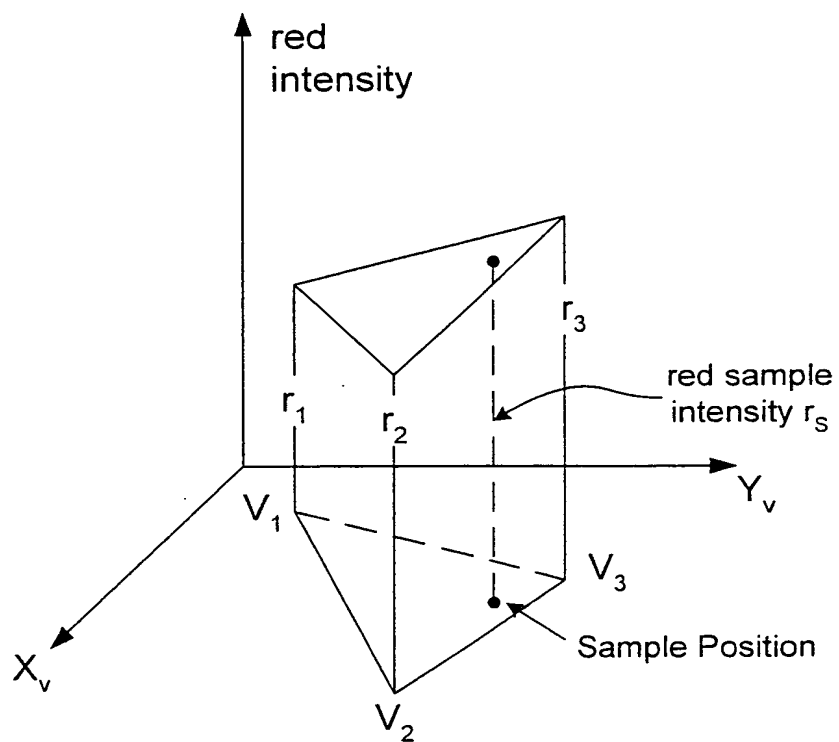


Fig. 7

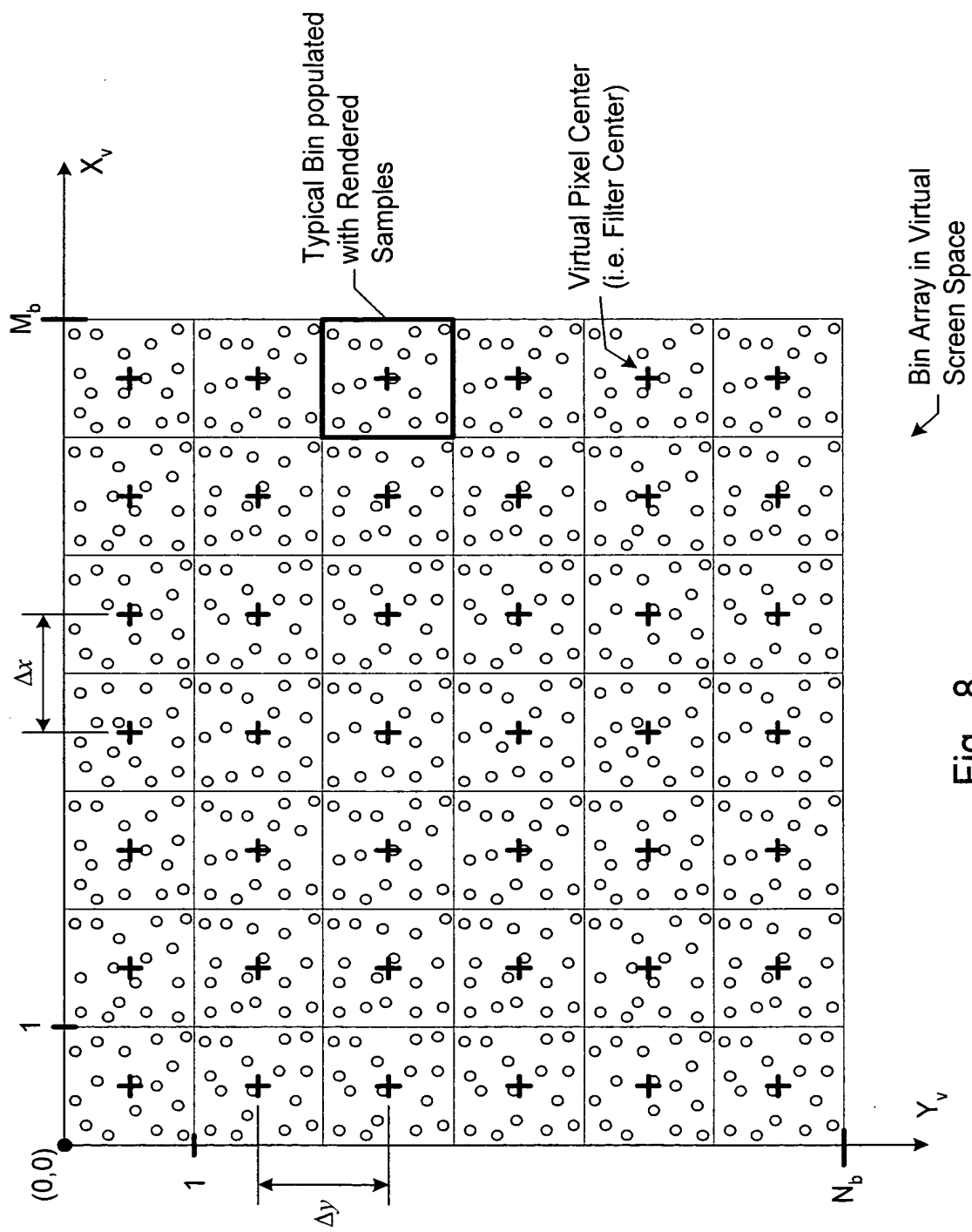


Fig. 8

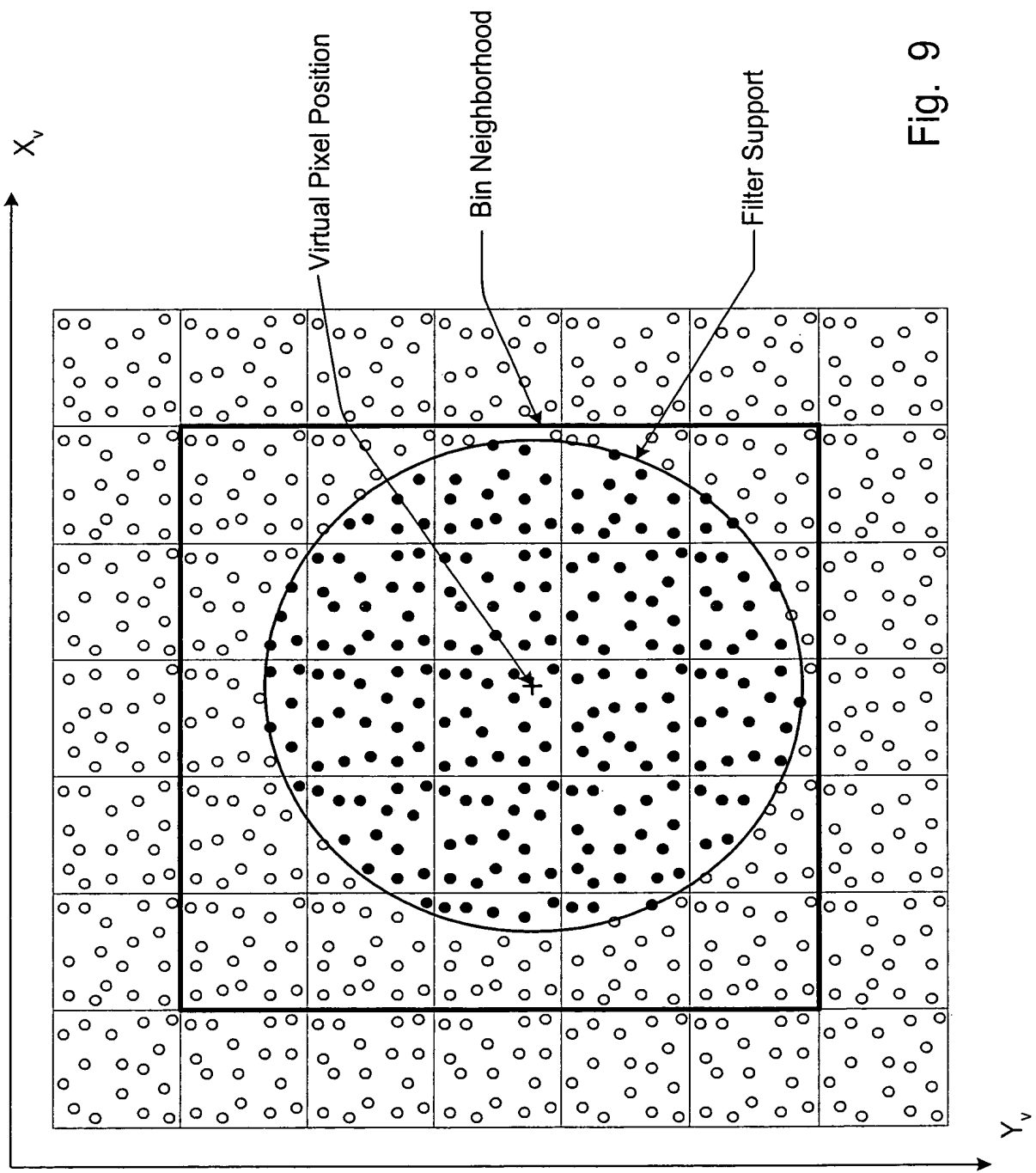


Fig. 9

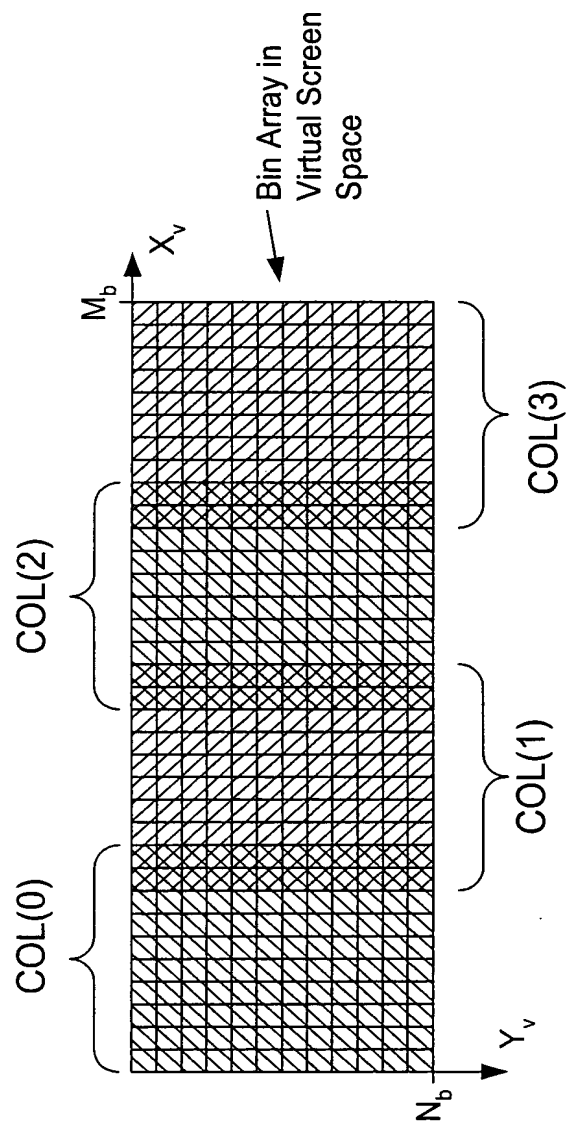


FIG. 10

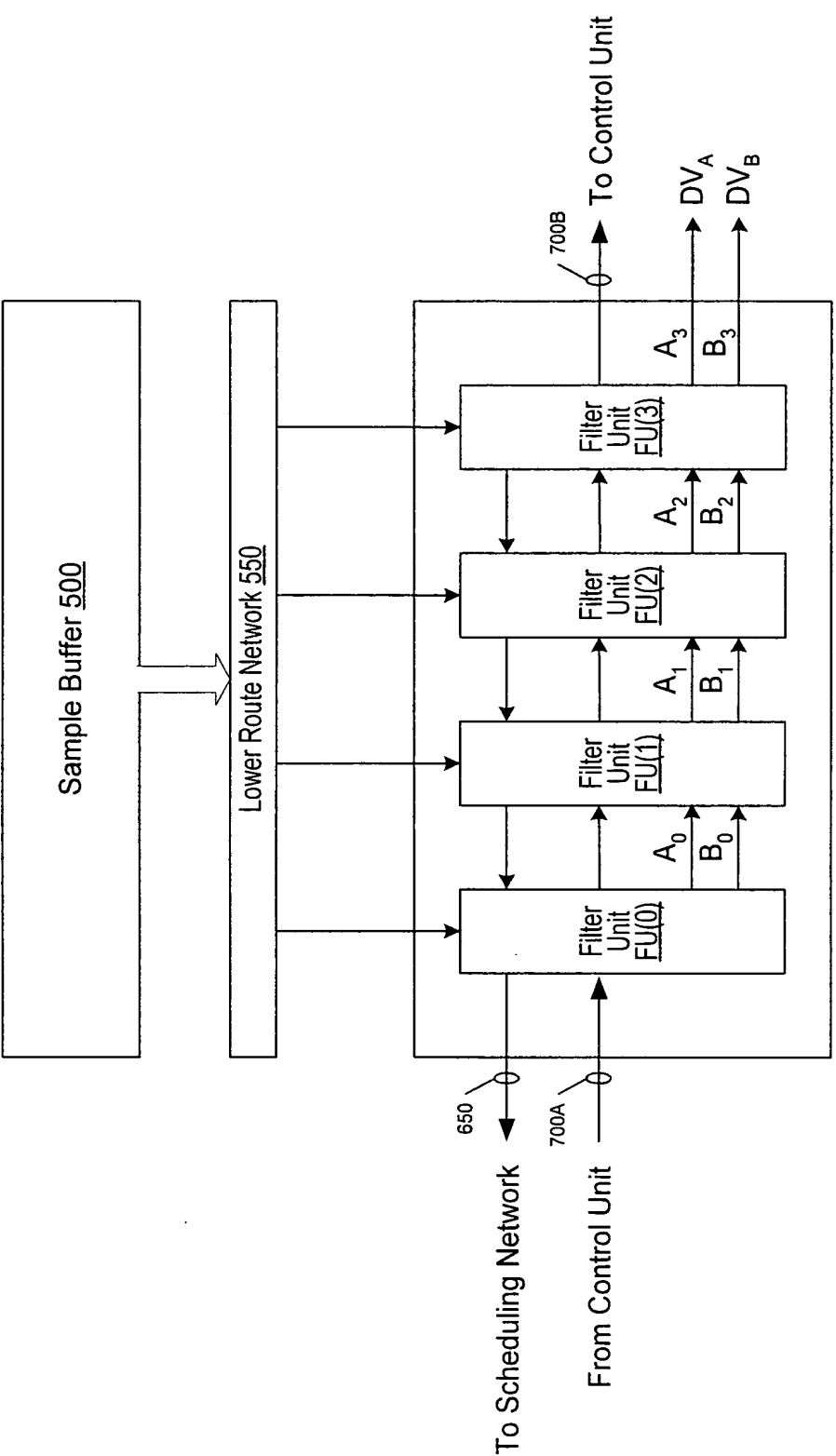


FIG. 11

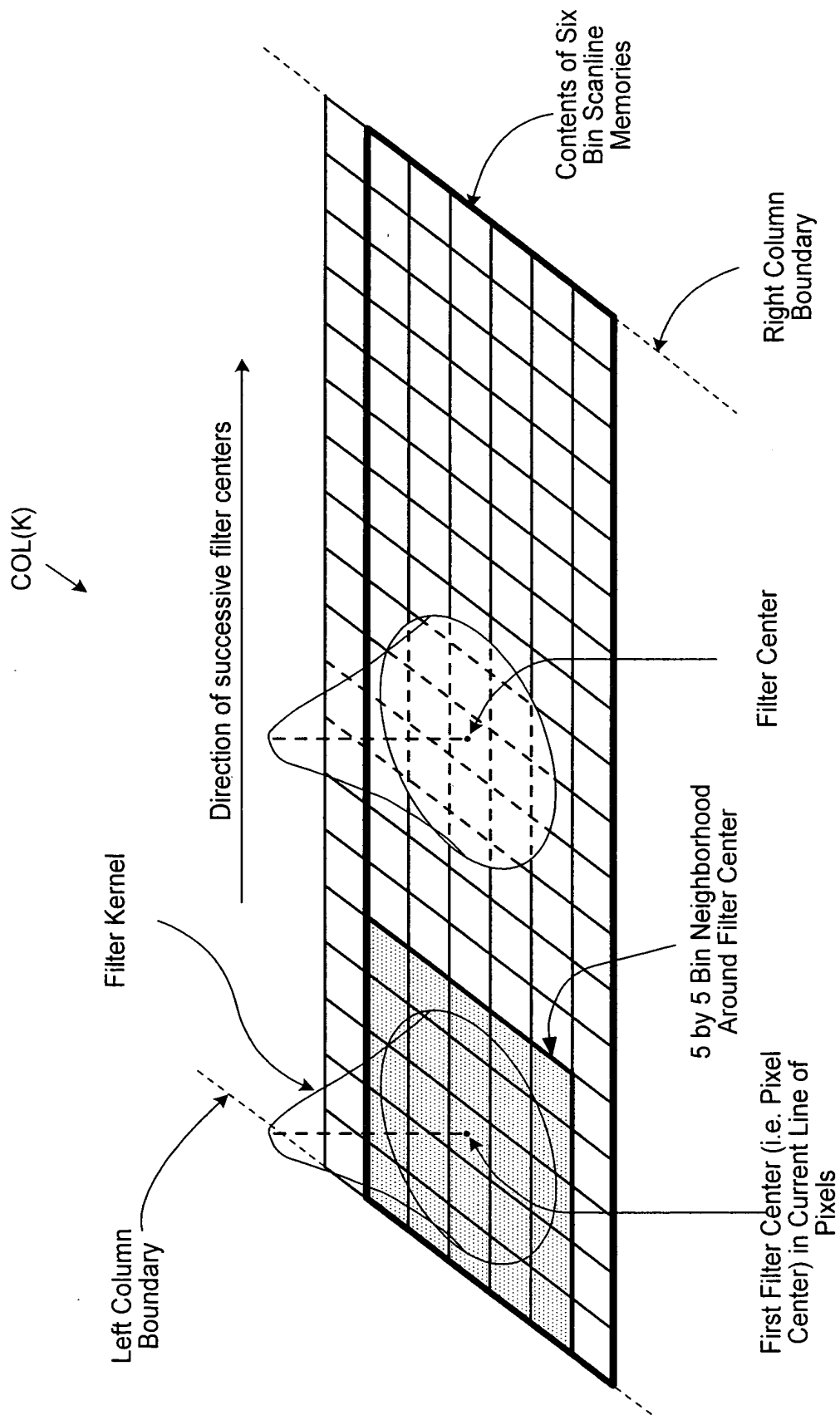


FIG. 12

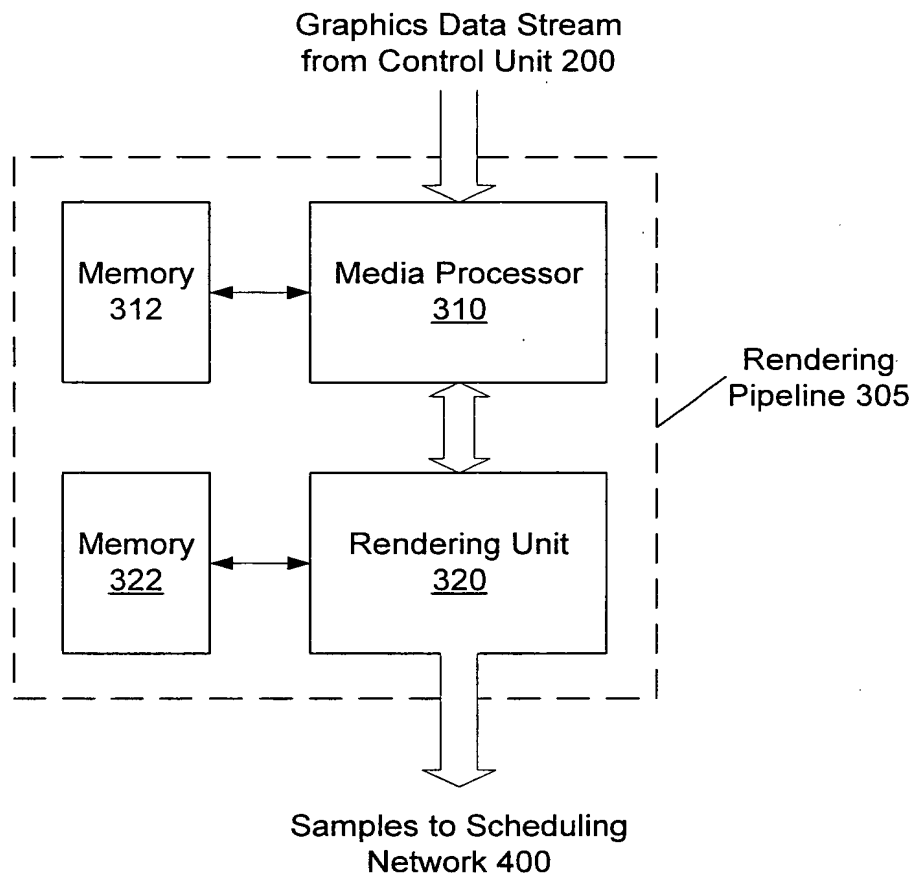


Fig. 13

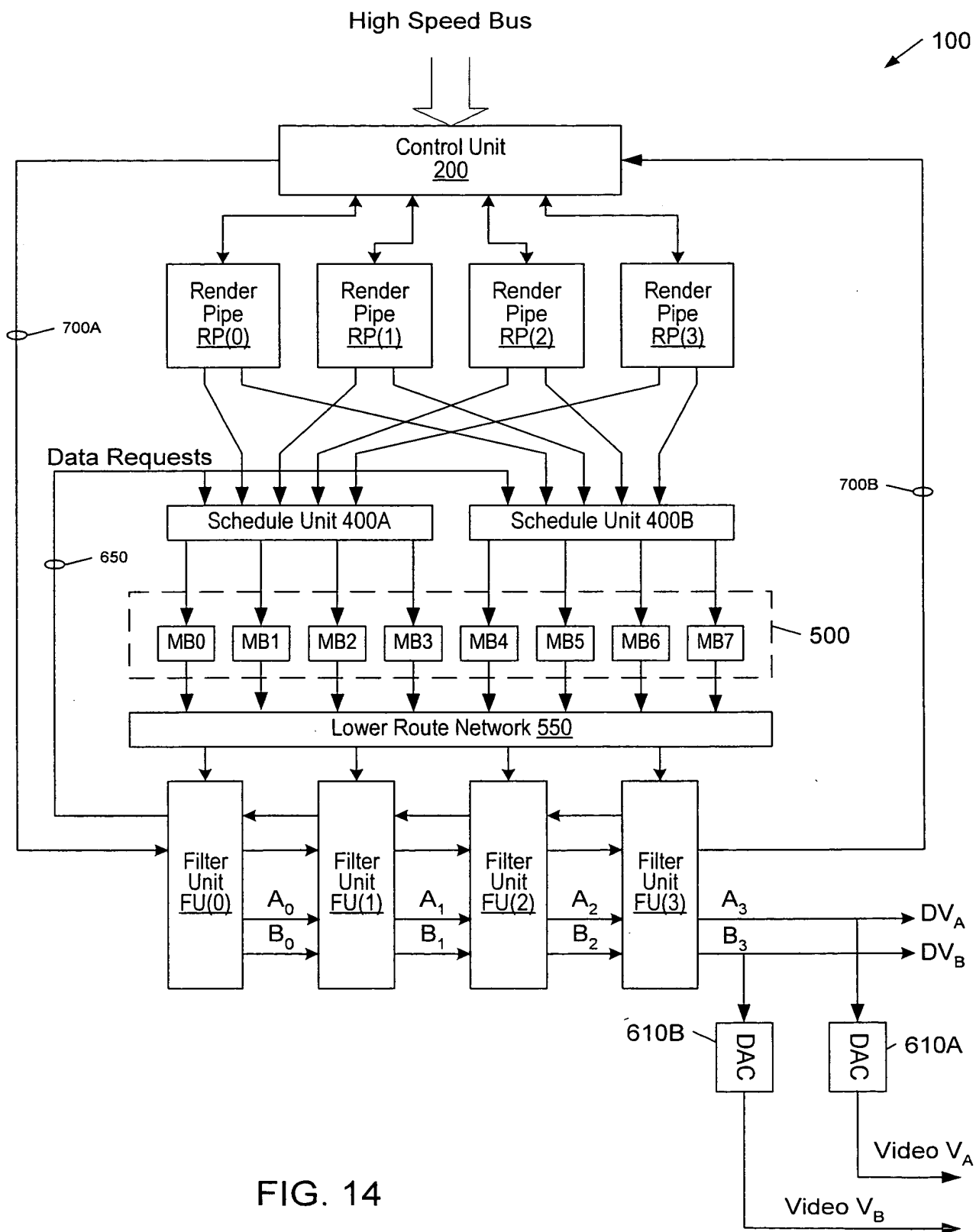


FIG. 14

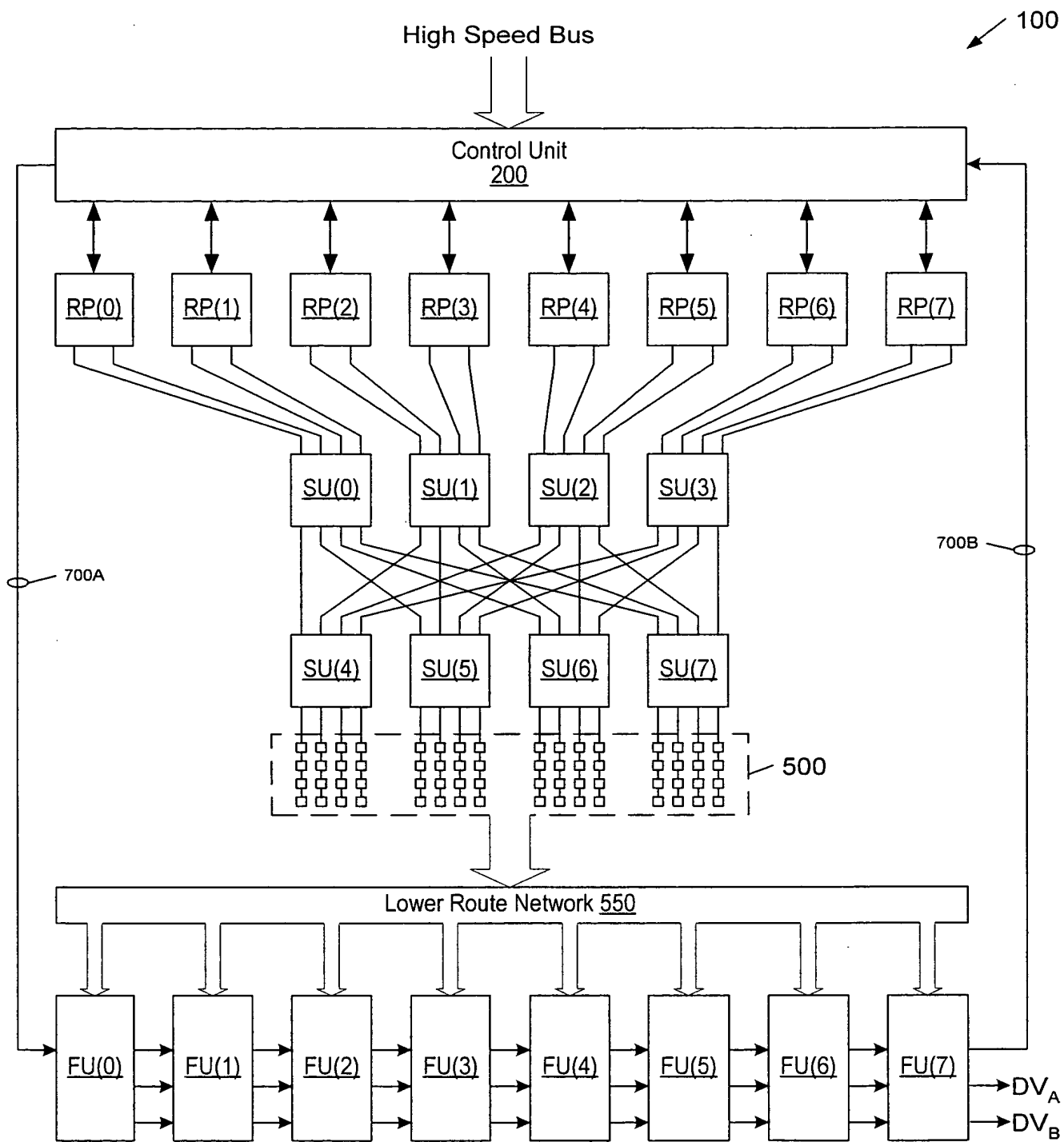


Fig. 15

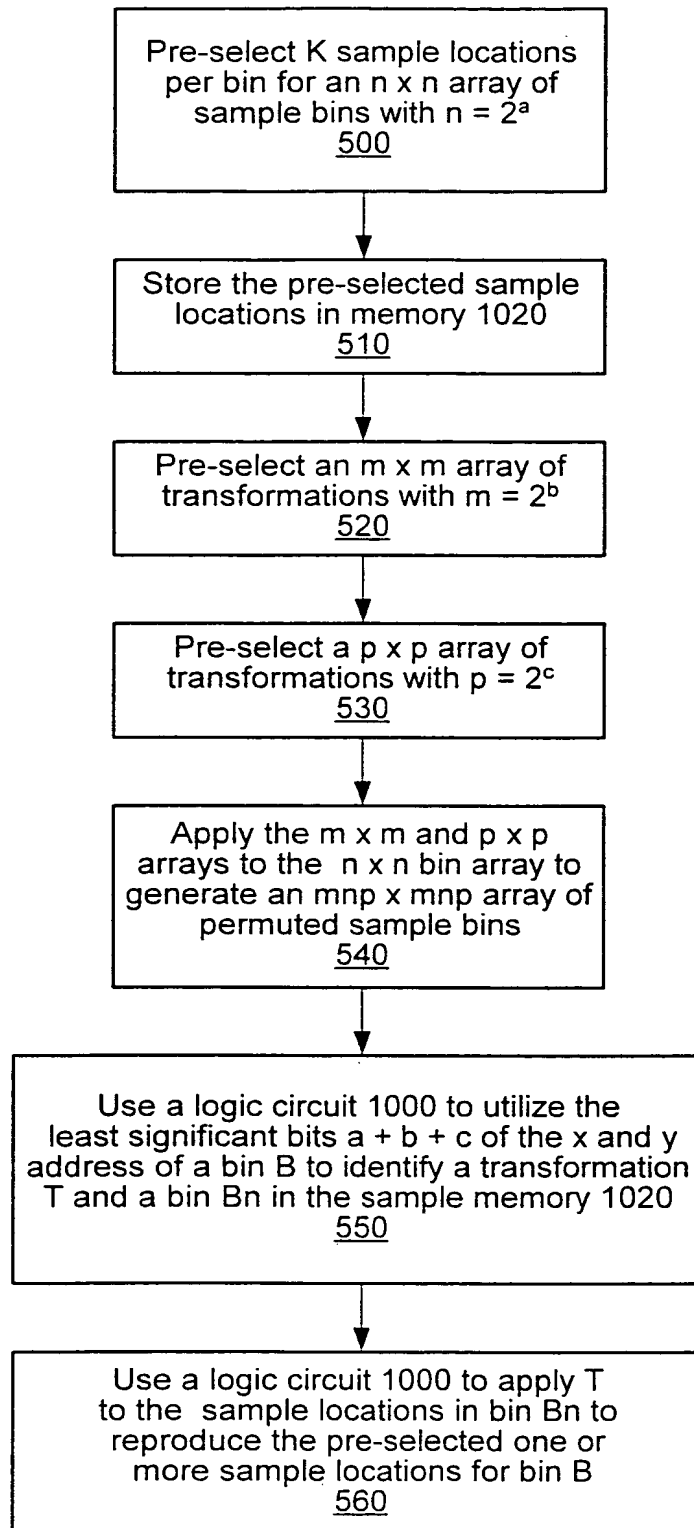


Fig. 16

Populate a 2 x 2 Sample Bin Array

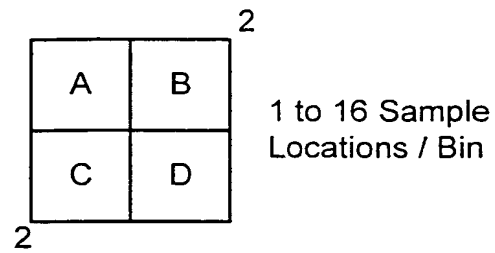


Fig. 17a

Select an Array of Transformations from:

iy	ix	s	Transformation
0	0	0	none
0	0	1	swapXY: mirror about $y = -x - 1$
0	1	0	invertX: mirror about y
0	1	1	rotate 270 degrees clockwise
1	0	0	invertY: mirror about x
1	0	1	rotate 90 degrees clockwise
1	1	0	rotate 180 degrees
1	1	1	mirror about $y = x$

Fig. 17b

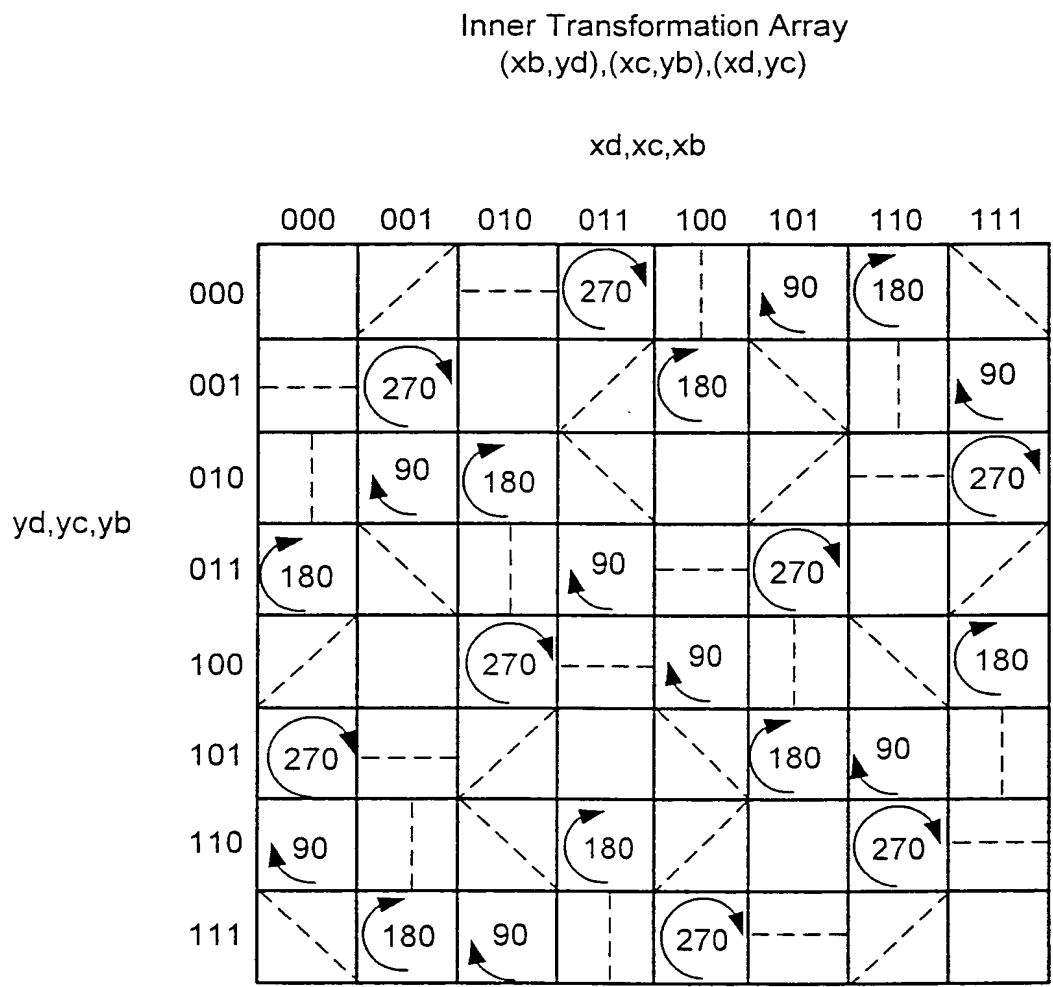


Fig. 18

Outer Transformation Array
 $(x_4, y_5), (x_6, y_4), (x_5, y_6)$

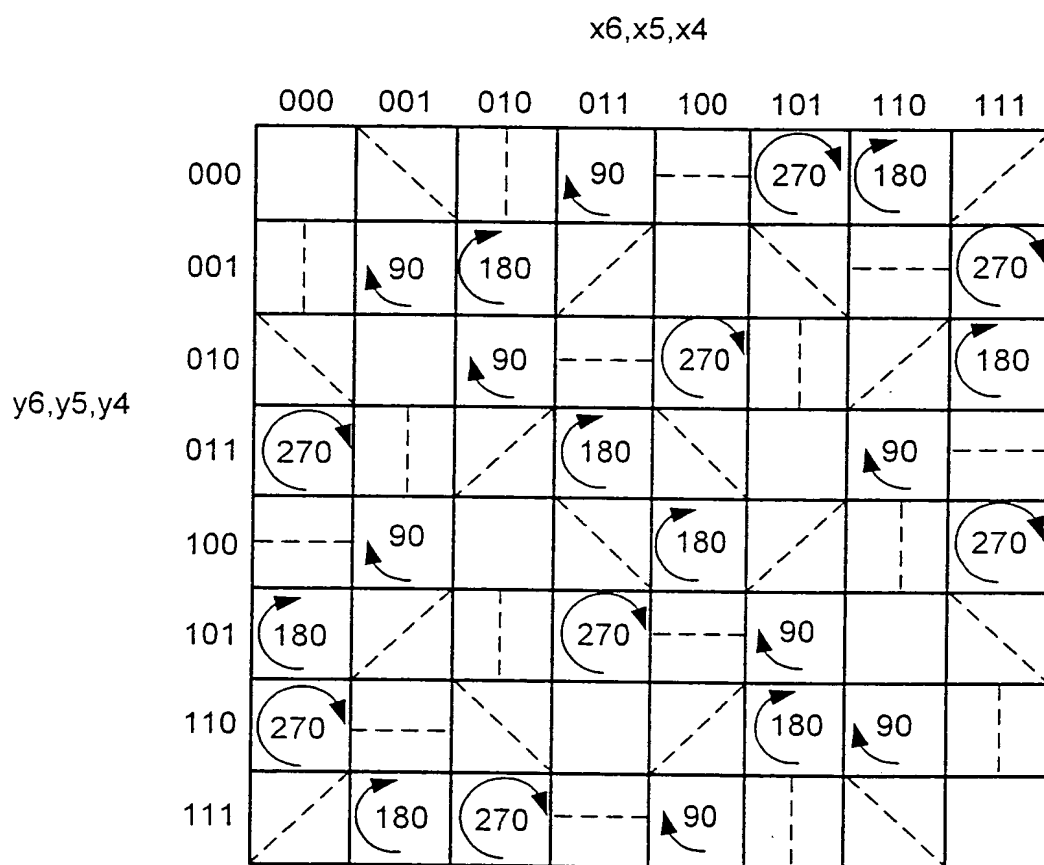


Fig. 19

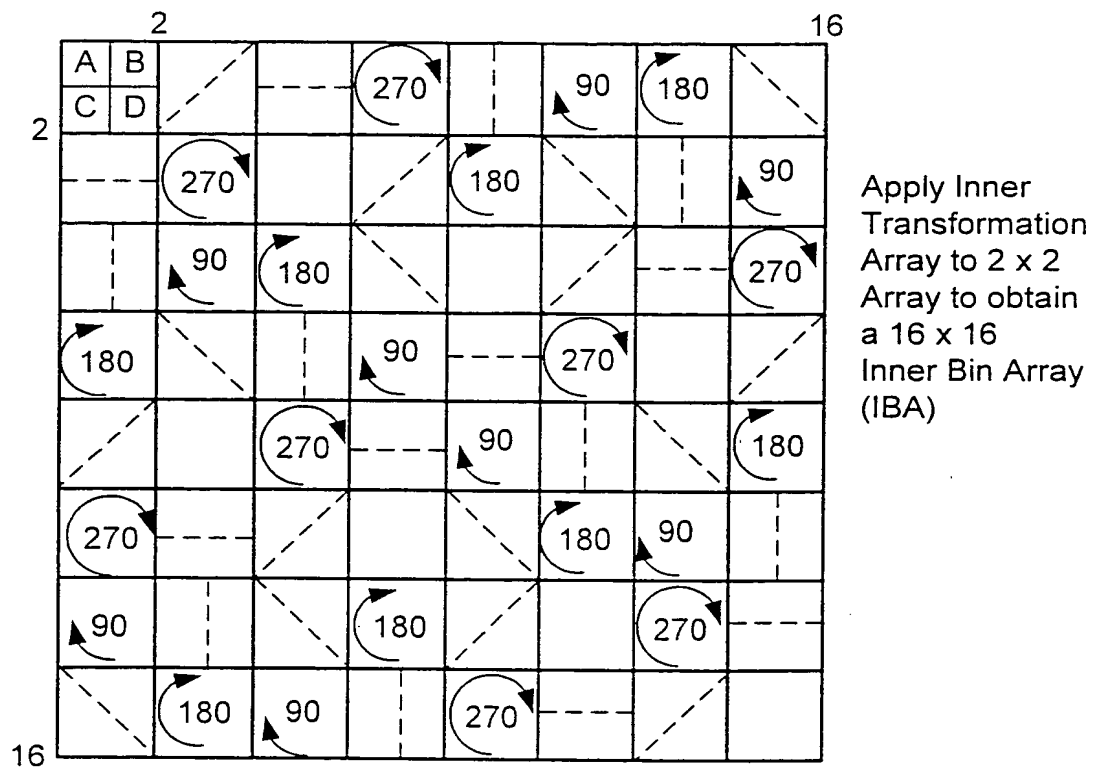


Fig. 20a

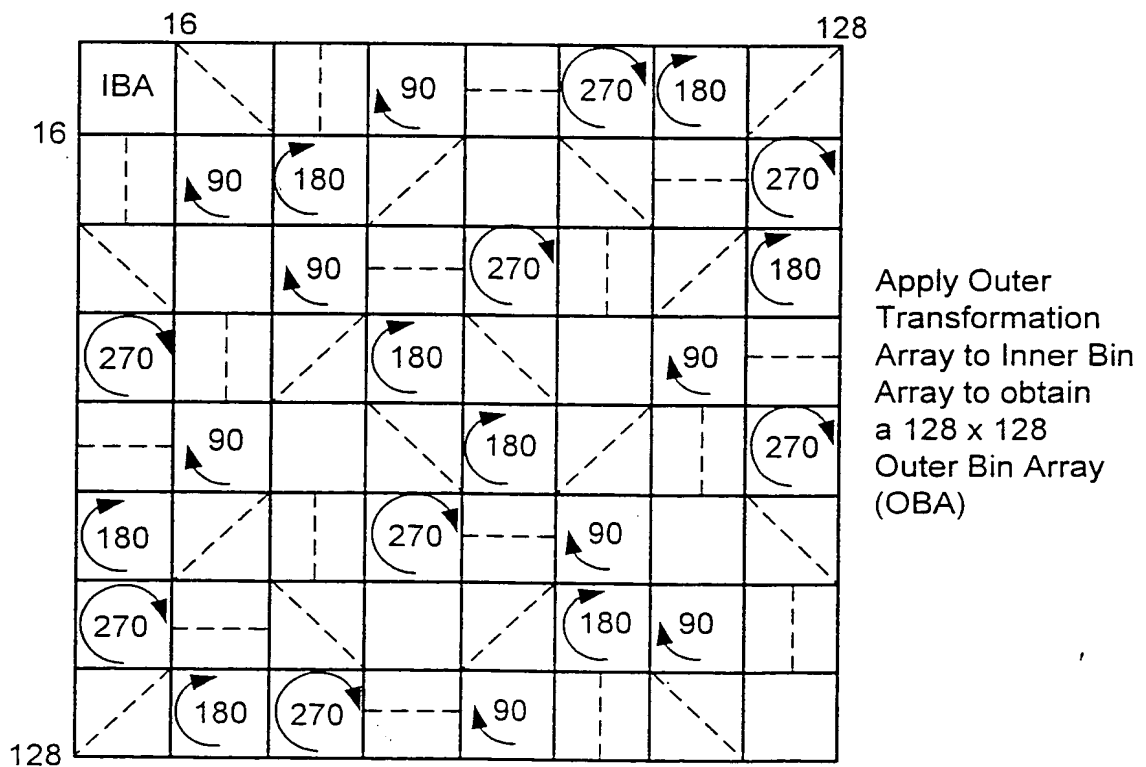


Fig. 20b

Tile Outer Bin Array To Fill Sample Space

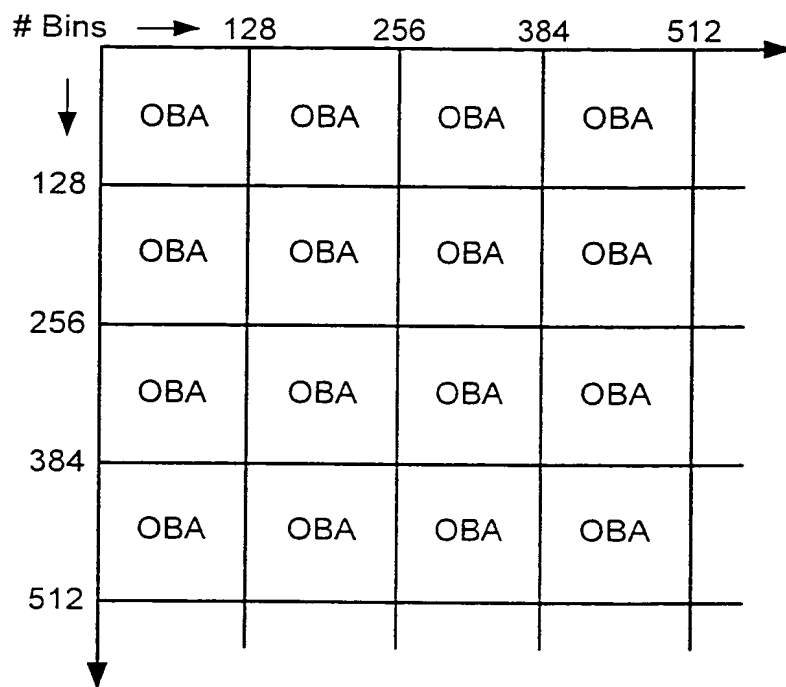


Fig. 20c

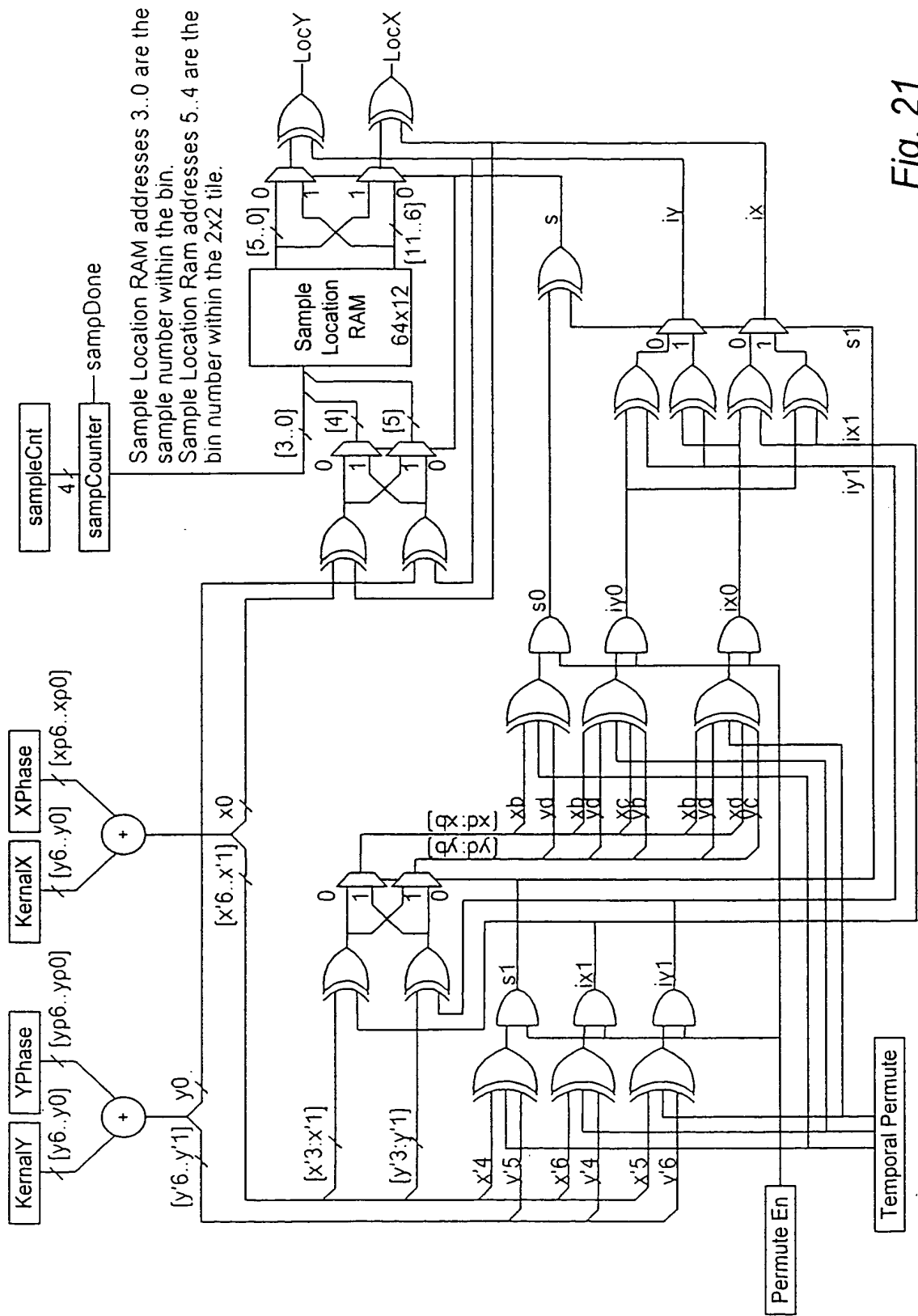


Fig. 21

Permutation Logic Circuit →

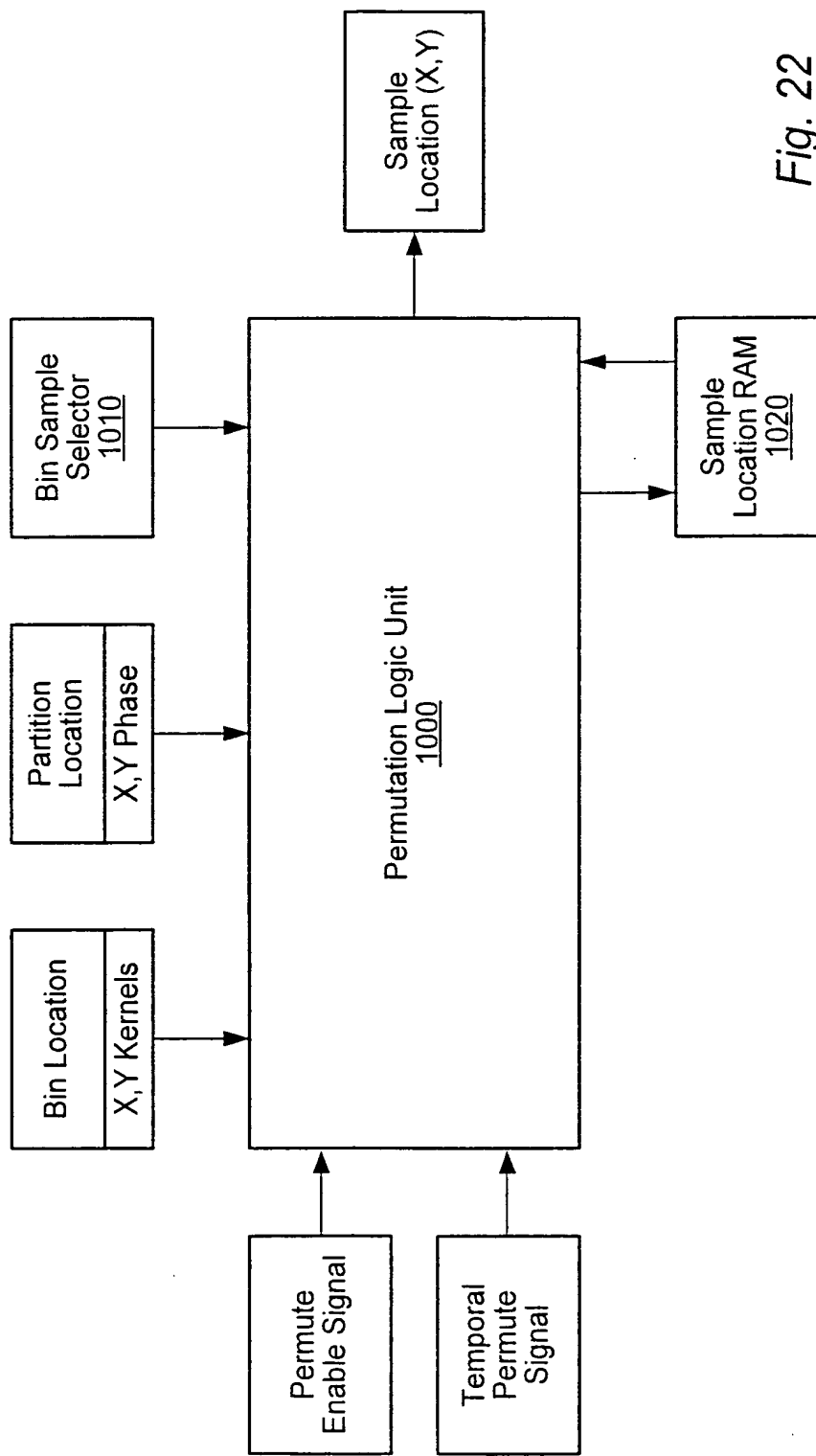
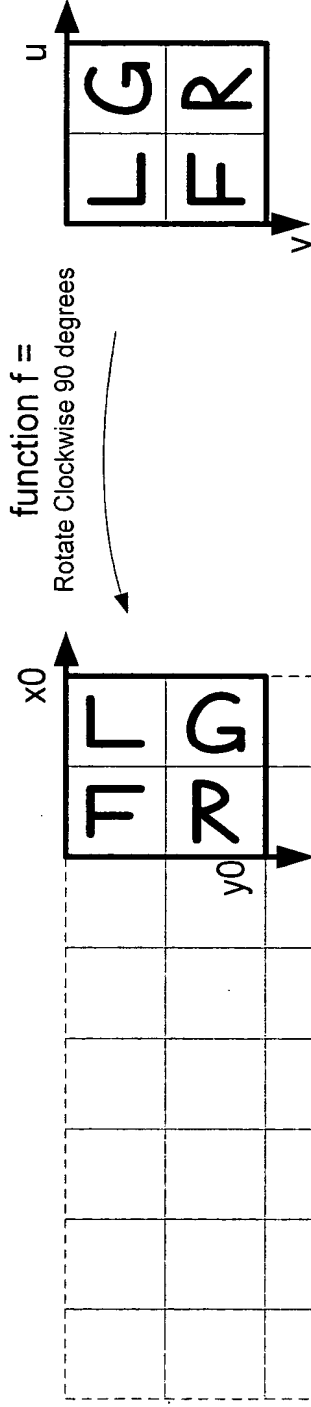


Fig. 22

Base Copy of Tile
Stored in Sample
Location RAM



Let U, V denote the addresses supplied to the sample location RAM. Transformations are applied to the base copy to build up an $N \times N$ pattern. Let $X0$ and $Y0$ denote the least significant bit of the X and Y bin address respectively. For a given transformation f , the addresses $x0$ and $y0$ are determined by applying the transformation f to u and v :

$$(x0, y0) = f(u, v).$$

But when using the sample generation circuit, we have $x0$ and $y0$ and want to compute u and v . So we apply the inverse function:

$$(u, v) = f^{-1}(x0, y0)$$

Fig. 23

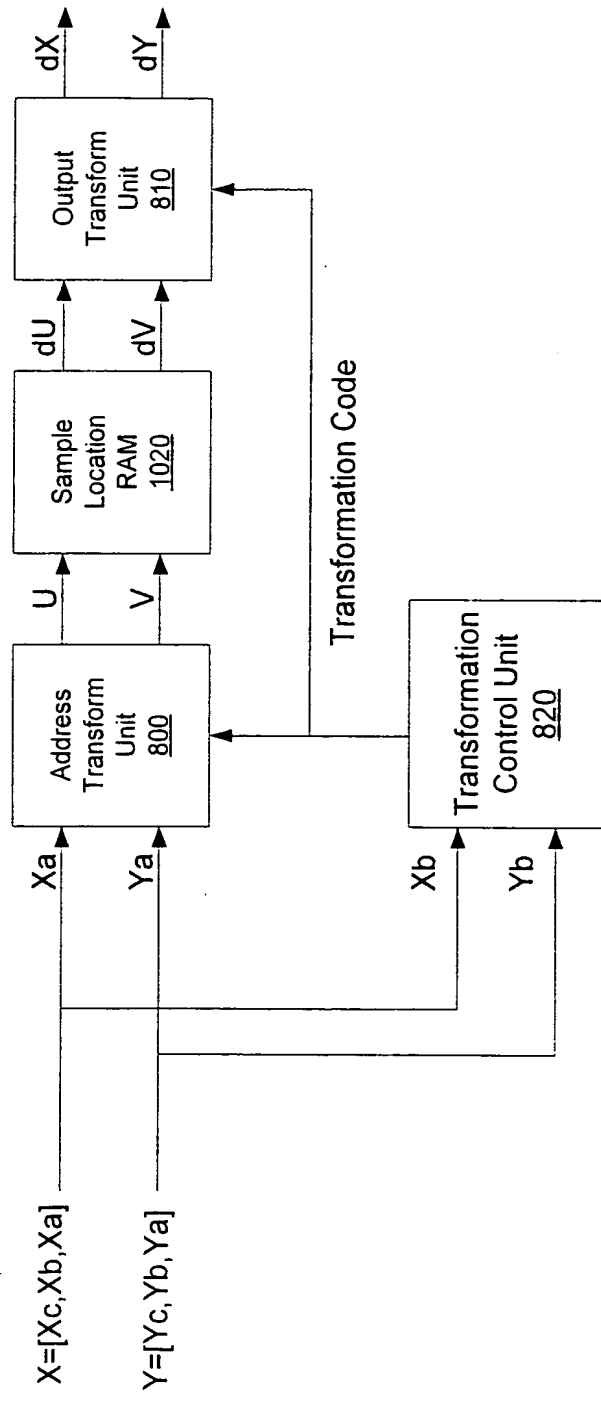


Fig. 24

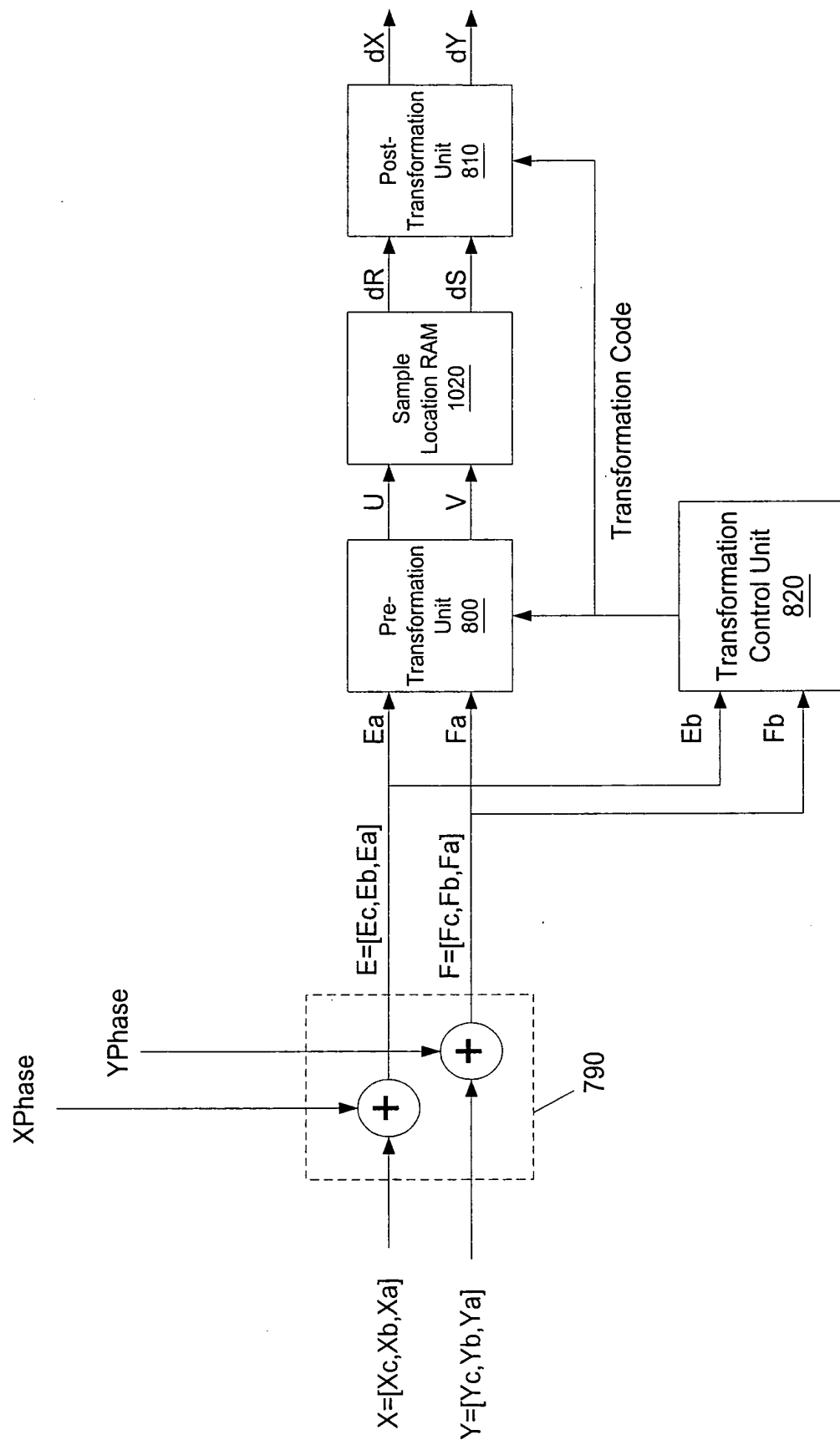


Fig. 25

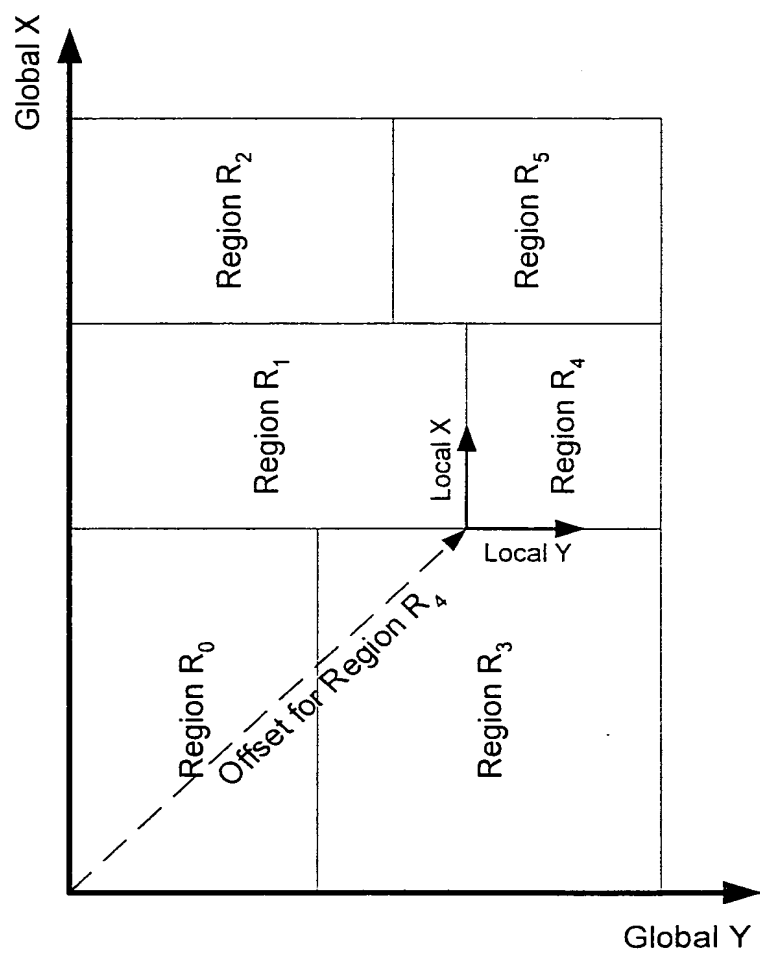


Fig. 26

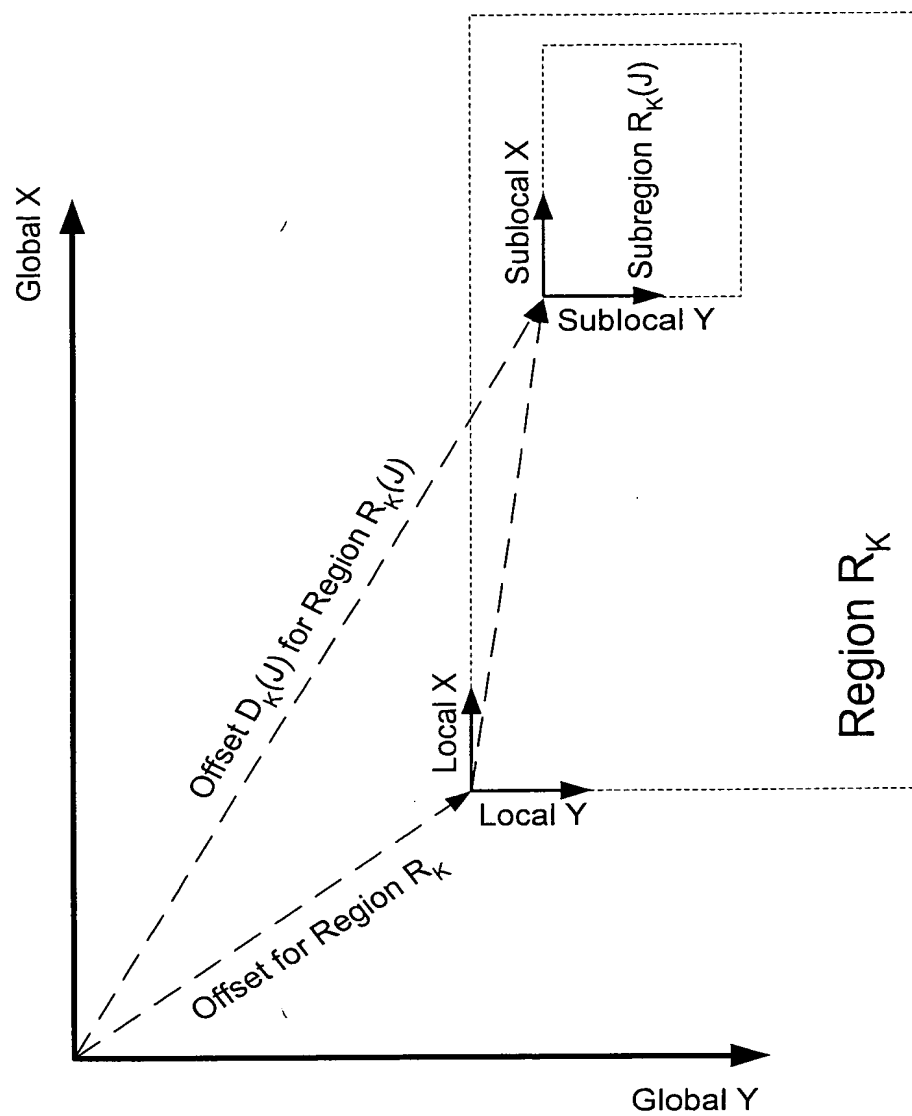


Fig. 27A

Sample Space Partitioned to 4 Filter Units

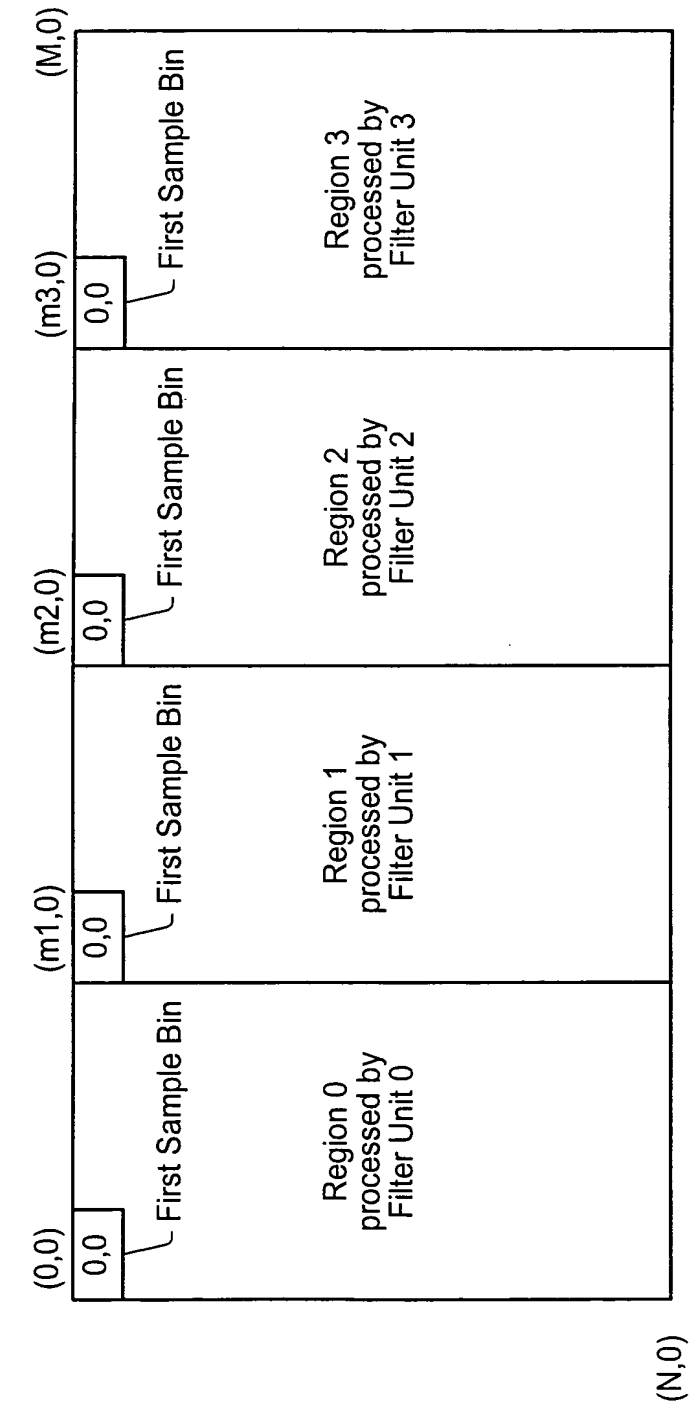


Fig. 27B

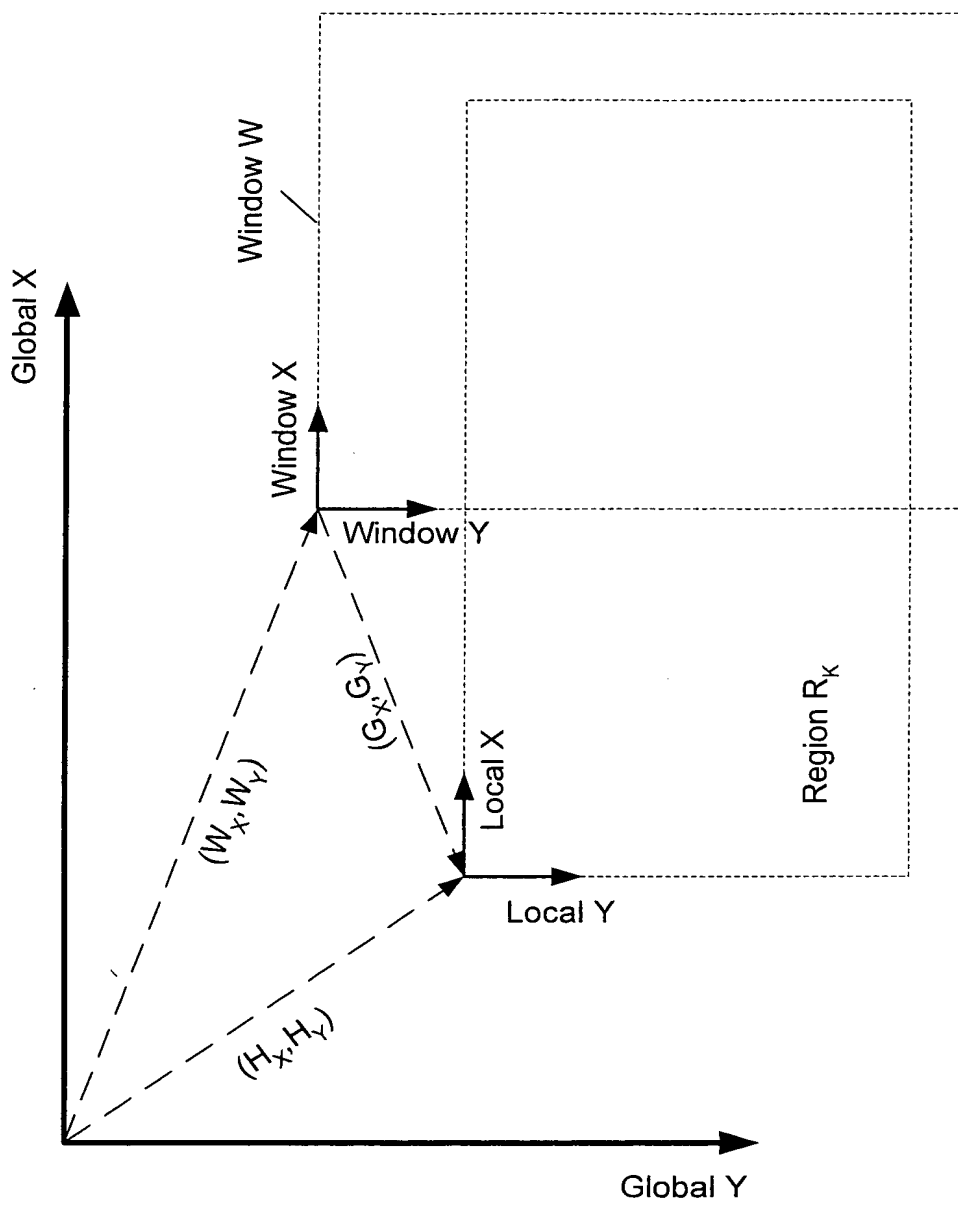


Fig. 28

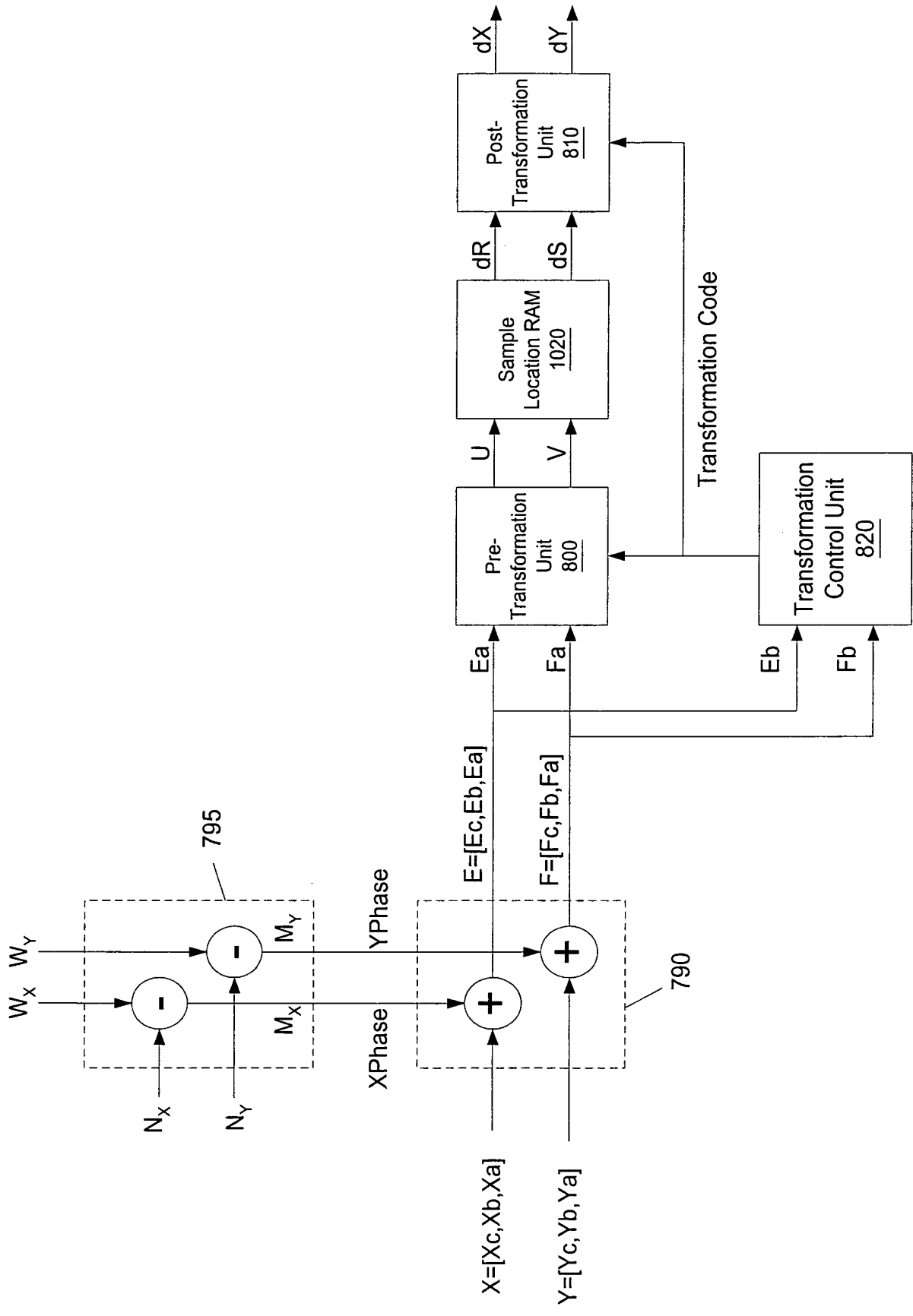


Fig. 29

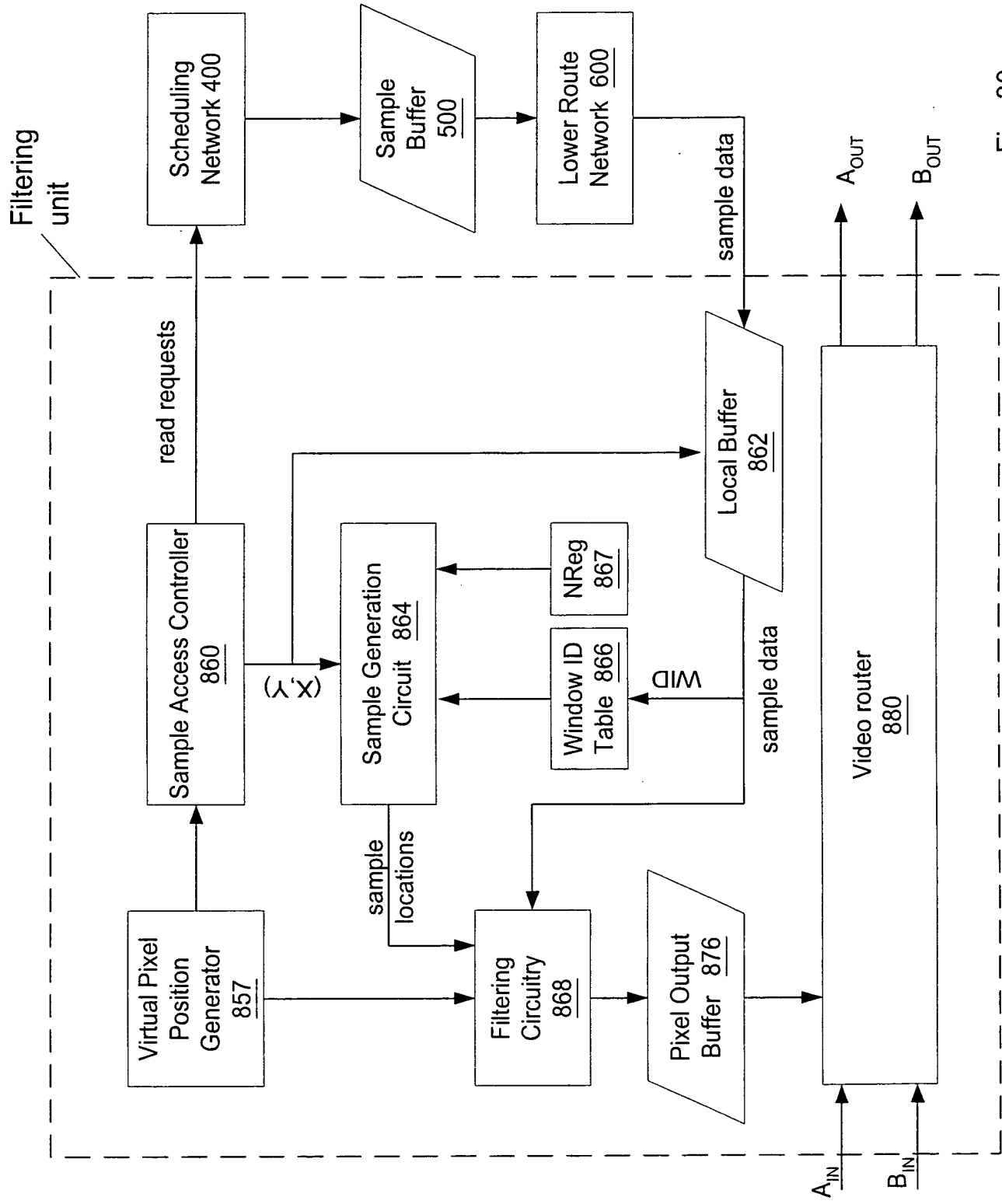


Fig. 30